

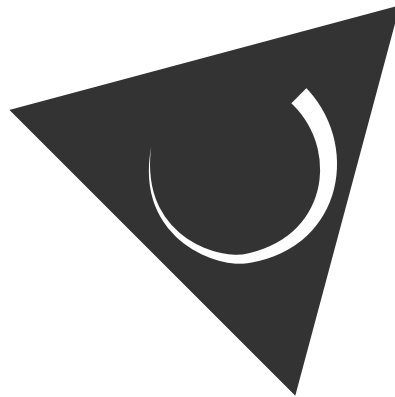
# Symmetry in Dynamical System Networks

Mehmet Ali Anil

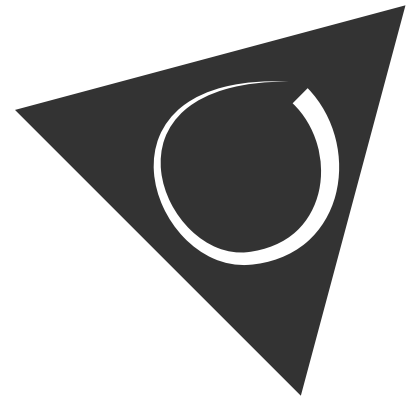
Symmetry is immunity to a possible change



120° rotation



240° rotation



360° rotation

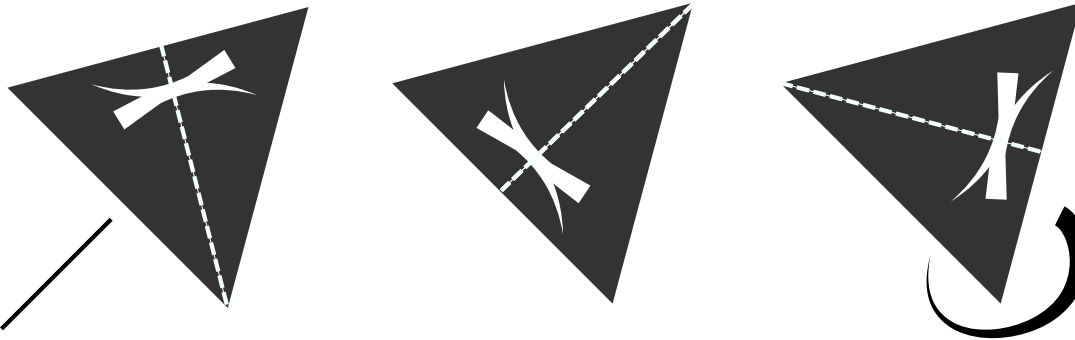
Cyclic  $\leftarrow Z_3$

# Symmetry operations form a group



they are closed

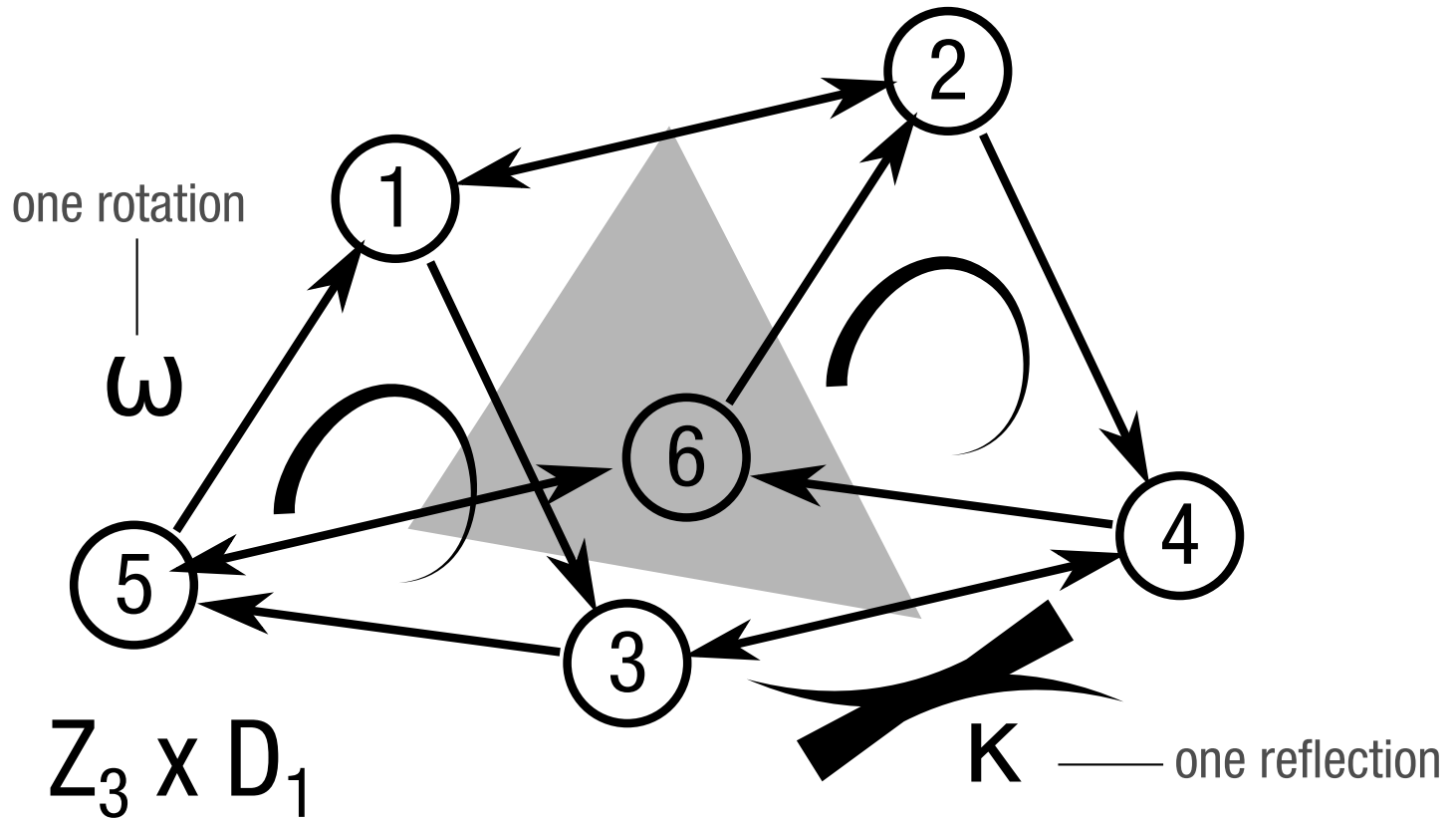
identity element



elements are operators

inverse element

# Networks can have symmetries



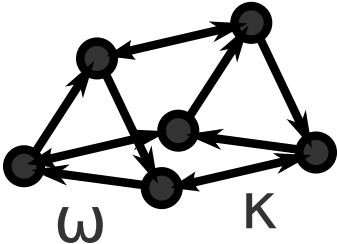
$$G = \{e, \omega, \omega^2, \kappa, \kappa\omega, \kappa\omega^2\}$$

Homomorphism is a structure preserving mapping with a twist

$$G = \{ \underbrace{e, \omega, \omega^2}_{\text{Ker}(\varphi)}, \underbrace{\kappa, \kappa\omega, \kappa\omega^2} \}$$

$$G' = \{ \underbrace{e', k', \dots}_{\text{Im}(\varphi)} \}$$

$\varphi$



$\gamma$  is a symmetry of a Dynamical System if it preserves all solutions to  $\dot{x}(t) = f(x)$

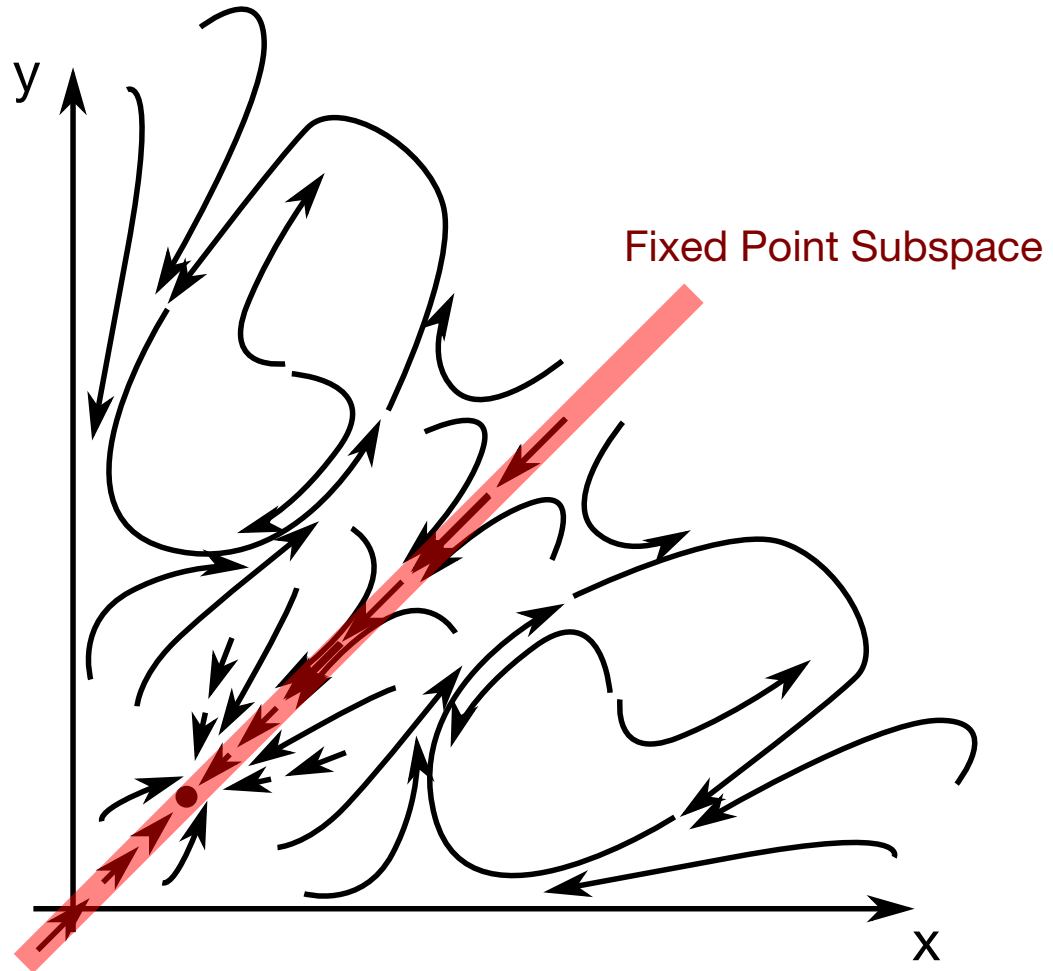
$$\dot{x}(t) = f(x)$$

dynamical system

$$\gamma \frac{\partial}{\partial t} x(t) = \frac{\partial}{\partial t} \gamma x(t) = f(\gamma x)$$

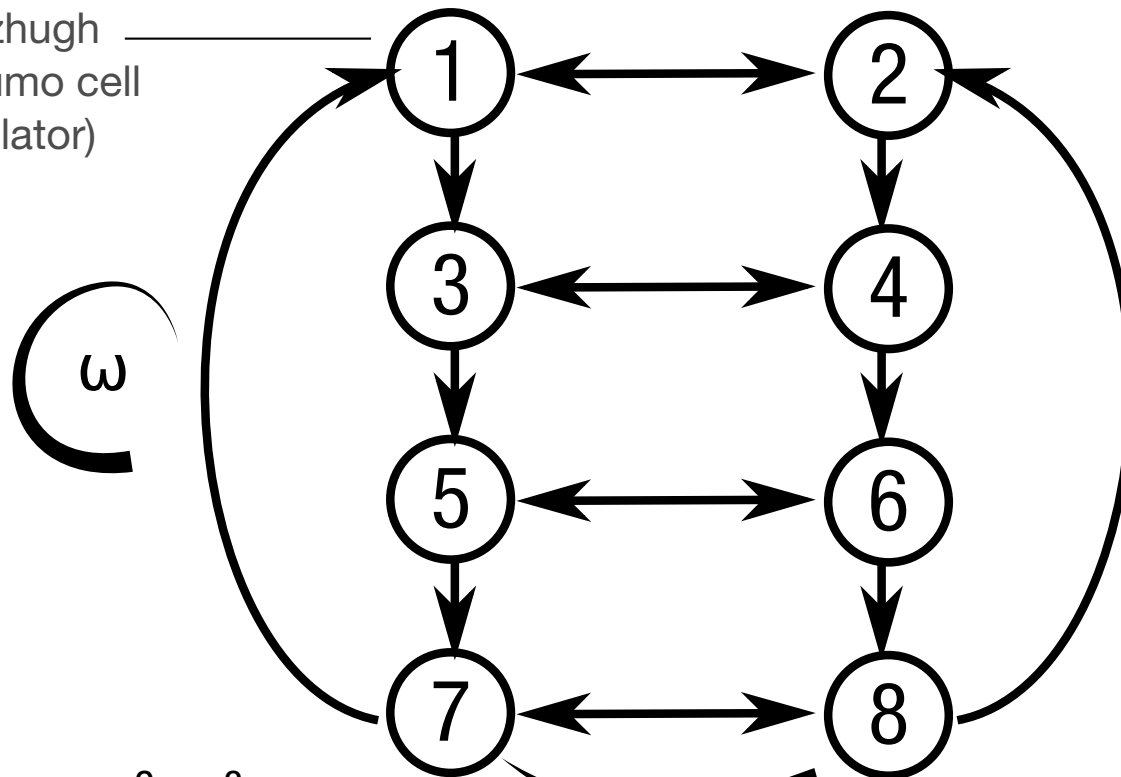
equivariance condition

A symmetry group fixes a subspace of the state space of the system



A neural network may have a symmetric coupling

a Fitzhugh  
Nagumo cell  
(oscillator)

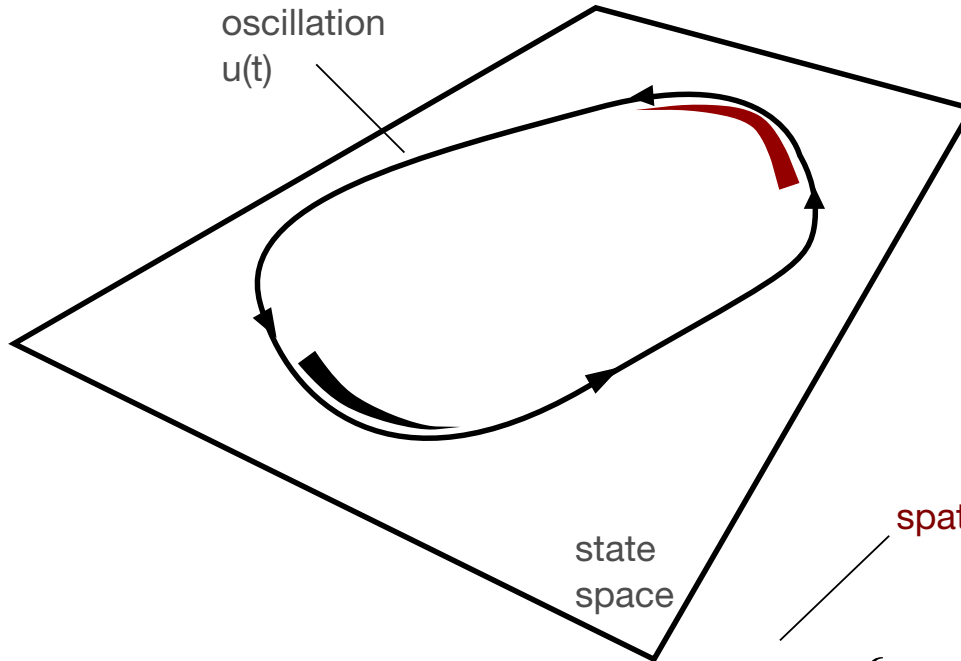


$$G = \{e, \omega, \omega^2, \omega^3, K, K\omega, K\omega^2, K\omega^3\}$$

$K$

$$\mathbf{Z}_4 \times \mathbf{D}_1$$

A symmetric network of oscillators will have two kinds of symmetries



spatiotemporal symmetries

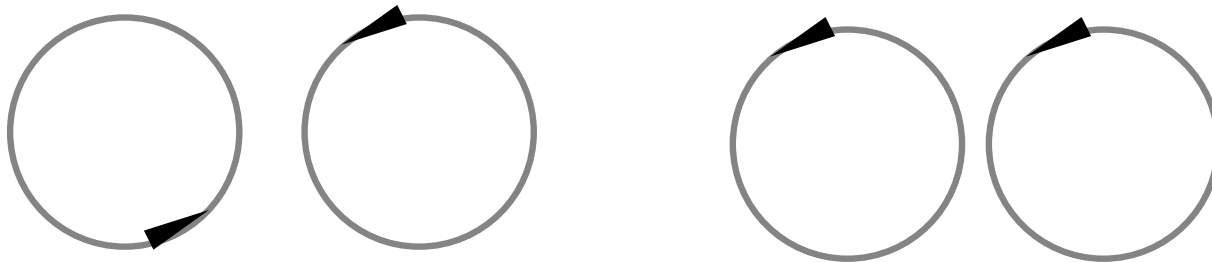
$$H = \{ \gamma \in G : \gamma \cdot \{u(t)\} = \{u(t)\} \}$$

spatial symmetries

$$K = \{ \gamma \in G : \gamma \cdot u(t) = u(t) \}$$

A phase difference between symmetrically coupled oscillators arise from  
a homomorphism

$$H = \{\gamma \in G : \gamma \cdot \{u(t)\} = \{u(t)\}\}$$

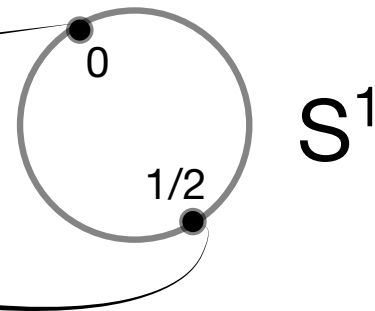


$$K = \{\gamma \in G : \gamma \cdot u(t) = u(t)\}$$

$$H = \{e, \omega, \omega^2, \omega^3\}$$

$$K = \{k, k\omega, k\omega^2, k\omega^3\}$$

$\varphi$



## First Isomorphism Theorem

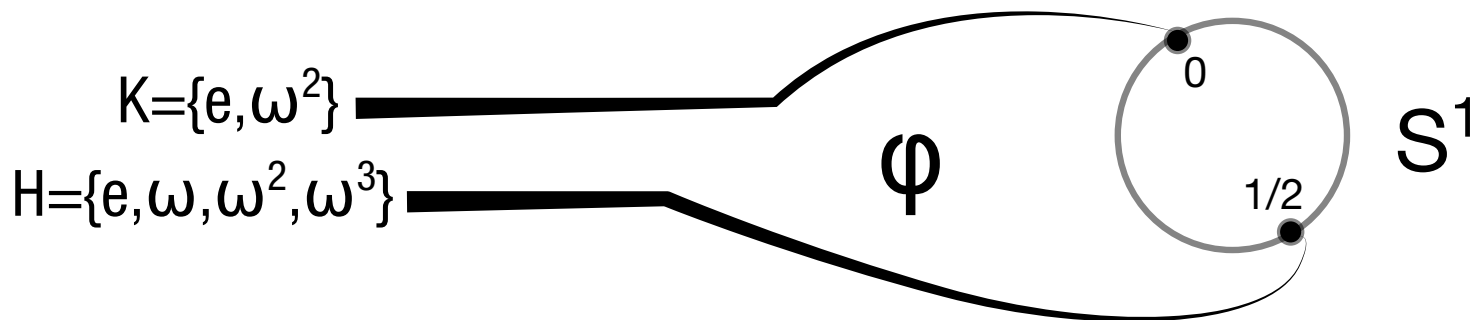
The image of  $\varphi$ ,  $\text{Im}(\varphi)$  is isomorphic to the closed quotient group  $H/K$ .

$$H = \{e, \omega, \omega^2, \omega^3\}$$

$$K = \{e, \omega^2\}$$

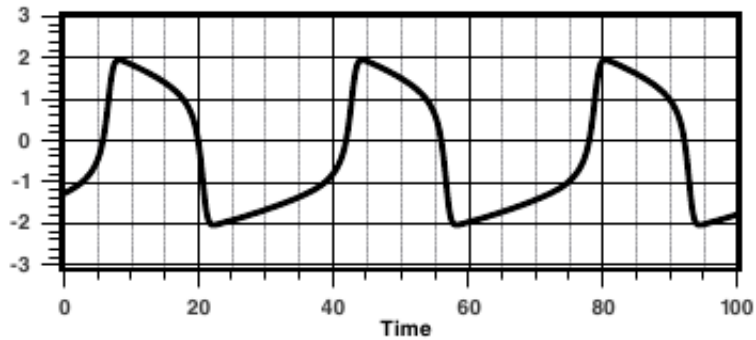
$$H / K = \{e \cdot \{e, \omega^2\}, \omega \cdot \{e, \omega^2\}, \omega^2 \cdot \{e, \omega^2\}, \omega^3 \cdot \{e, \omega^2\}\}$$

$$H / K = \{\{e, \omega^2\}, \{\omega, \omega^3\}, \{\omega^2, e\}, \{\omega^3, \omega\}\}$$
$$= \{\{e, \omega^2\}, \{\omega, \omega^3\}\} \cong \mathbf{Z}_2$$

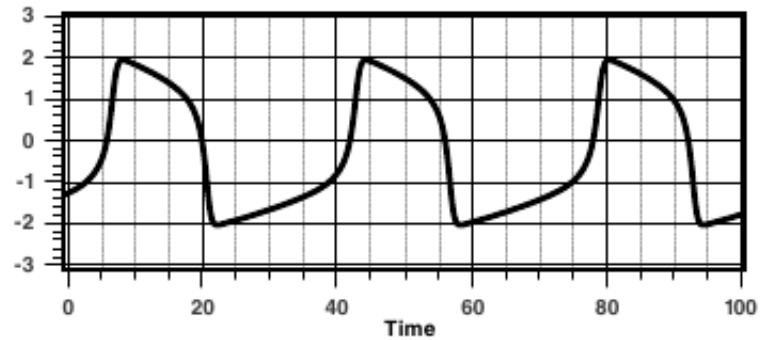


Numerical simulations also confirm the presence of such solutions  
 $H=\{e,\omega,\omega^2,\omega^3\}$   $K=\{e,\omega^2\}$

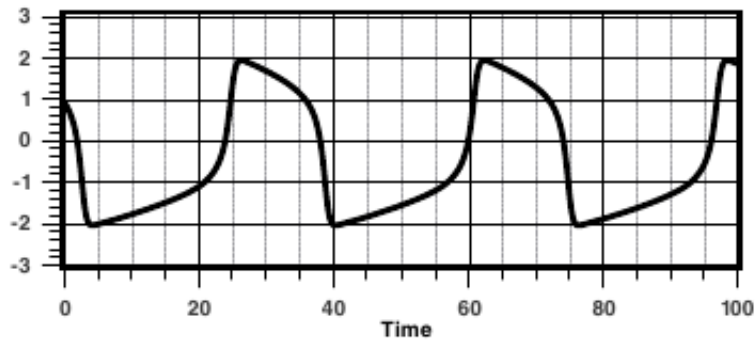
V5



V6



V7



V8

